



Measuring the Performance Impact of Branching Instructions

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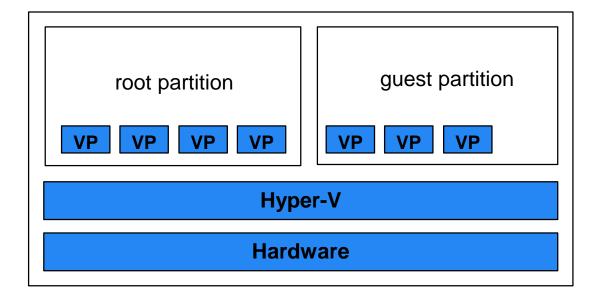
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https://se.informatik.uni-wuerzburg.de

Motivation: Performance is important!

- Case example: Stress testing Microsoft's Hyper-V hypervisor
- Repeated addition and removal of a virtual processor

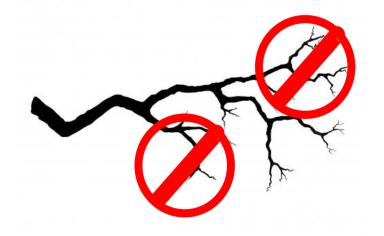




- Unproblematic at lower execution speed
- Crash likelihood increases with execution speed

Related work: How can the cost of branch executions be reduced [1, 2, 3]

> Here: We can avoid branches – what is the performance gain?

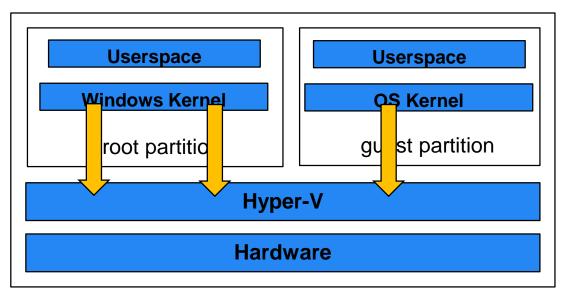




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Background: Hyper-V

- Type I-hypervisor
- Virtual machines are called partitions
- Microkernel-architecture: outsouring of functionality into a privileged virtual machine (the "root partition")



Partitions can request hypervisor services using hypercalls



Microsoft

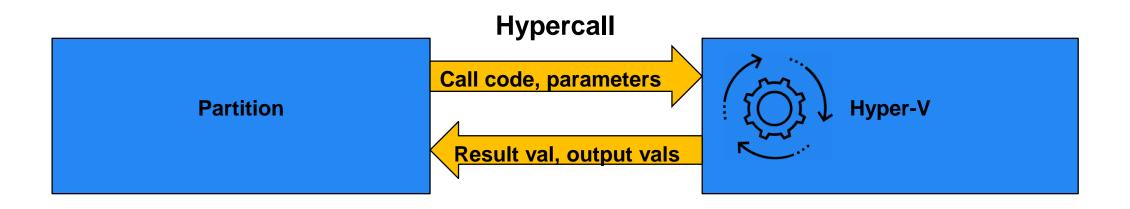
Hyper-v

Background: Hypercalls

> Examples:

- HvCreatePartition
- HvCreateVp (virtual processor)
- HvNotifyLongSpinWait

→	nput Parameter Header		
0	PartitionId (8 bytes)		
8	VpIndex (4 bytes)	TargetVtl (1 byte)	RsvdZ (3 bytes)





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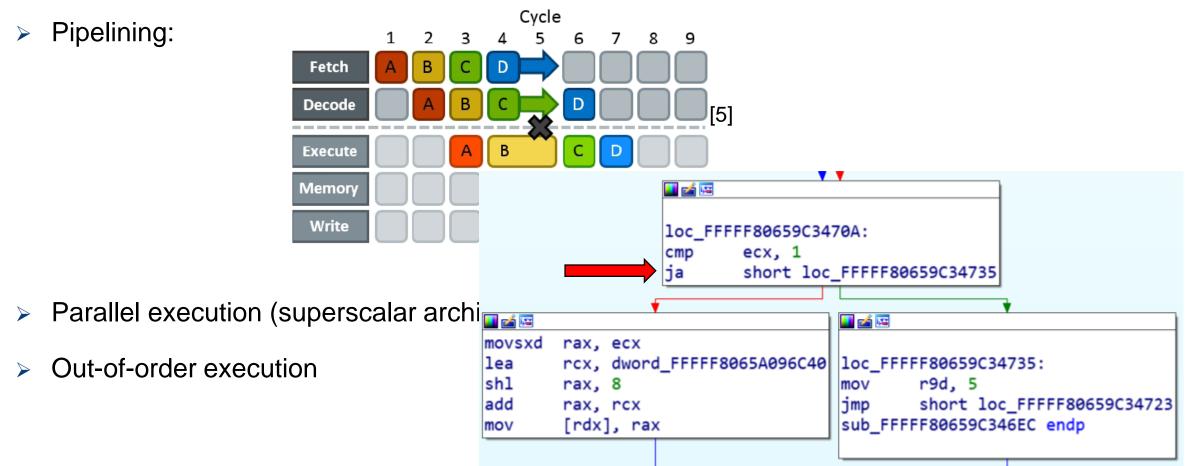
Background: Hypercall Injector

- Windows kernel module (proposed at SSP 2019 [4])
- Can inject arbitrary hypercalls into Hyper-V
- Logging for these values is possible:
 - Result value
 - Output values
 - Timesteps
 - Execution time
- Logging is optional
 - Memory constraints
 - Execution overhead



Background: Branching

> Processors try to parallelize instruction execution as much as possible



Branches: Next instruction unclear, speculative execution



Research Question

- Goal is highest throughput for stress testing
- No values will be logged

What is the cost of checking if something should be logged, if nothing is logged?

- Certainly branchless will be faster
- Branches always take the same branch, so by how much?



Execution Loop with Branches

```
// prepare
1
  while (/* more to execute */) {
2
       switch (/* type */) {
3
       case TYPE_WAIT:
4
           // sleep and maybe log times, details left out
5
           break;
6
       case TYPE_CALL:
7
           // prepare memory for call
8
           if (/* timesteps or execution time requested */)
9
               // take start time
10
           // issue hypercall
11
           if (/* timesteps or execution time requested */)
12
               // take end time
13
           if (/* timesteps requested */)
14
               // store time stamps
15
           if (/* execution time requested */)
16
               // calculate execution time and store
17
           if (/* result value requested */)
18
               // store result value
19
           if (/* output values requested /*)
20
               // store output memory page
21
22
23
```

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Execution Loop without branches

```
// prepare
1
  while (/* more to execute */) {
2
       switch (/* type */) {
3
       case TYPE_WAIT:
4
            // sleep and maybe log times, details left out
5
            break;
6
       case TYPE_CALL:
7
            // prepare memory for call
8
9
10
            // issue hypercall
11
12
13
14
15
16
17
18
19
20
21
22
23 }
```

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The Disadvantage...

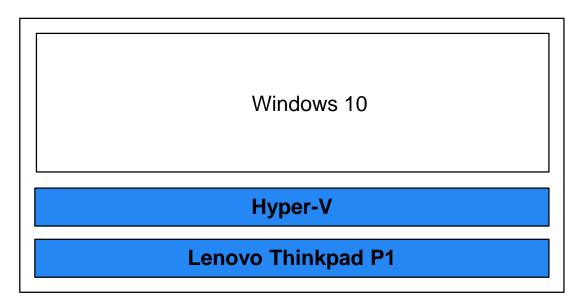
Choosing correct loop beforehand based on request log values

- if (flags_received->memory && !flags_received->exectime && !flags_received->timestamps && !flags_received->result && !flags_received->output)
 status = perform_memory(input_file, output_file);
- else if (flags_received->memory && !flags_received->exectime && !flags_received->timestamps && flags_received->result && !flags_received->output)
 status = perform_memory_log_result(input_file, output_file);
- else if (flags_received->memory && !flags_received->exectime && !flags_received->timestamps && !flags_received->result && flags_received->output)
 status = perform_memory_log_output(input_file, output_file);
- else if (flags_received->memory && !flags_received->exectime && !flags_received->timestamps && flags_received->result && flags_received->output)
 status = perform_memory_log_result_output(input_file, output_file);
- else if (flags_received->memory && flags_received->exectime && !flags_received->timestamps && !flags_received->result && !flags_received->output)
 status = perform_memory_log_exectime(input_file, output_file);
- else if (flags_received->memory && flags_received->exectime && !flags_received->timestamps && flags_received->result && !flags_received->output)
 status = perform_memory_log_exectime_result(input_file, output_file);

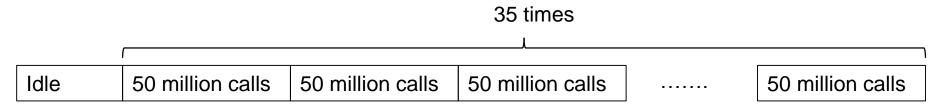
Around 40 implementations of the essentially the same code...



Measurement Methodology



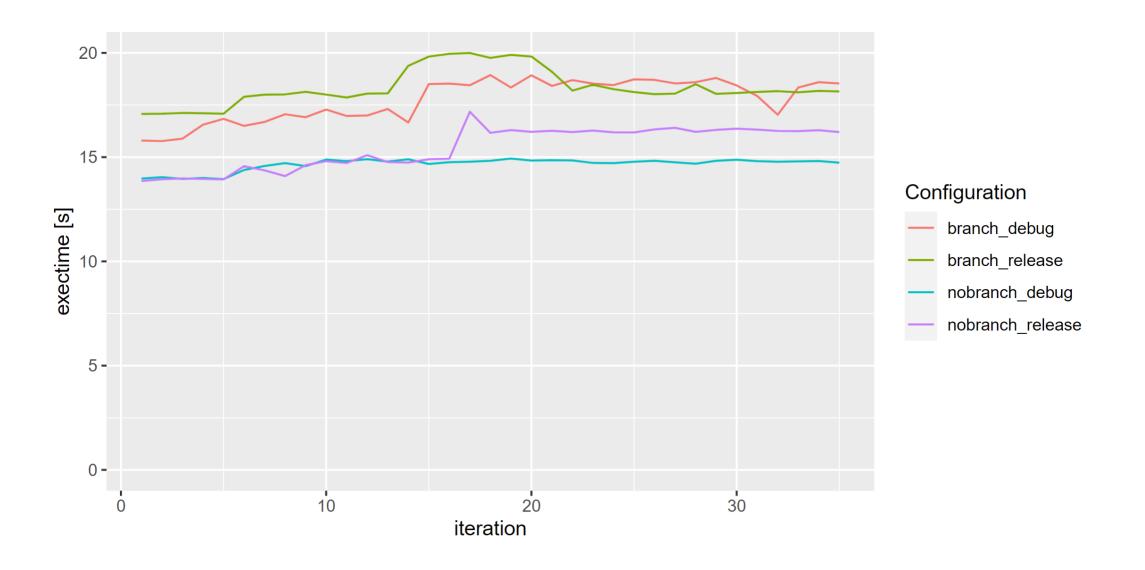
- > Test campaign: 50 million invalid hypercall
- Execution time is measured; can be used to calculate throughput
- Execution of 35 consecutive runs





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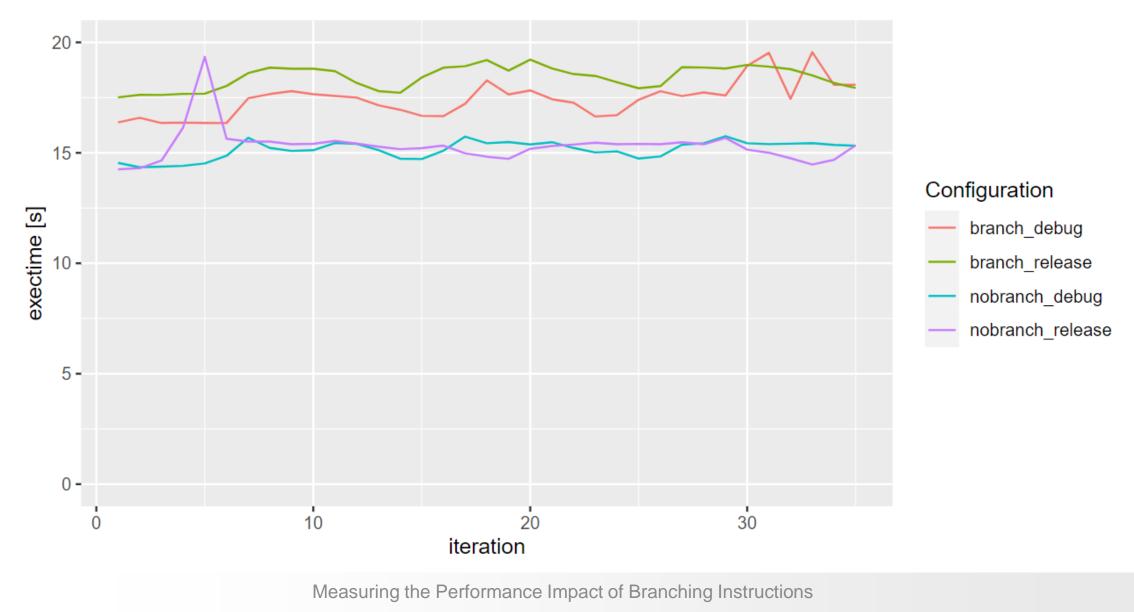
Results



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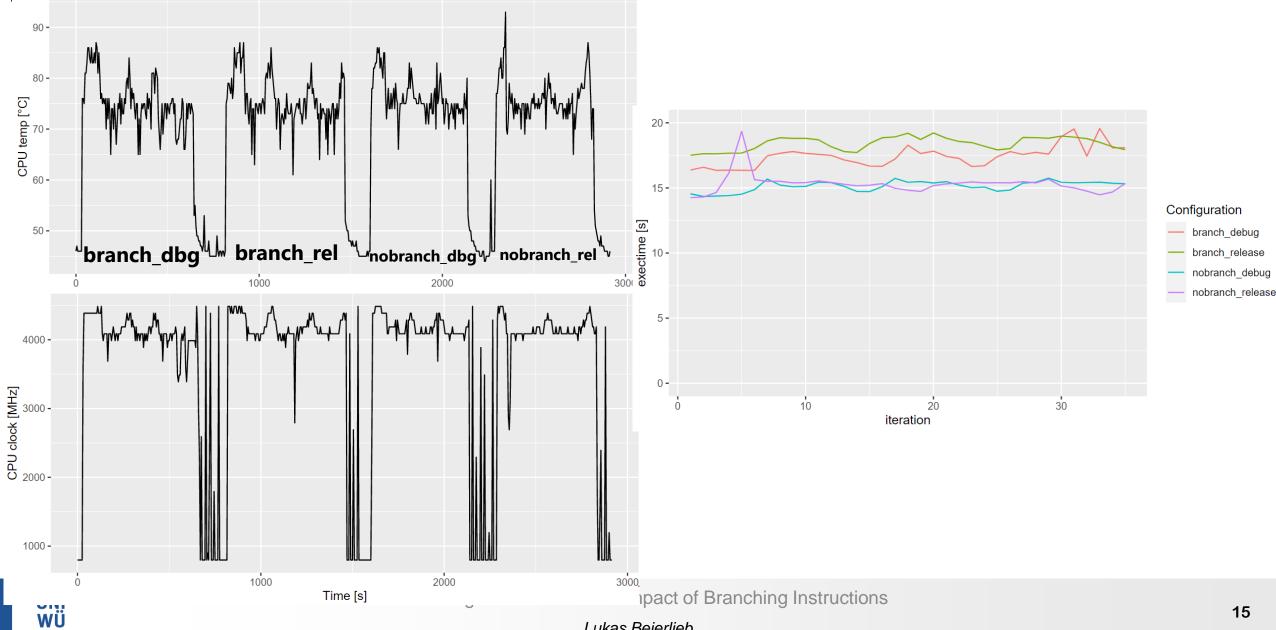
Further Measurements



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Additional Data



Summary

- Testing tools require high performance for stress testing
- Idea: try to minimize overhead by reducing branching instructions (used for logging)
- Effects are significant

- > Compromise:
 - Use dedicated branchless implementation for high throughput configurations (no logging, only execution times)
 - Use branch-based implementation to cover all other cases
 - Performance gains where required
 - Small penalty for maintainability





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References

[1] Hwu, W. et al.: Comparing software and hardware schemes for reducing the cost of branches

[2] McFarling, S. et al.: Reducing the cost of branches

[3] Kim, H. et al.: Vpc prediction: reducing thecost of indirect branches via hardware-based dynamic devirtualization

[4] Beierlieb, L. et al.: Towards Testing the Performance Influence of Hypervisor Hypercall Interface Behavior

[5] <u>https://www.intel.com/content/www/us/en/developer/tools/oneapi/tech-articles-how-to/overview.html#gs.fw8np8</u>



The End

Thank you for your attention!



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